

Living the Loopless Life

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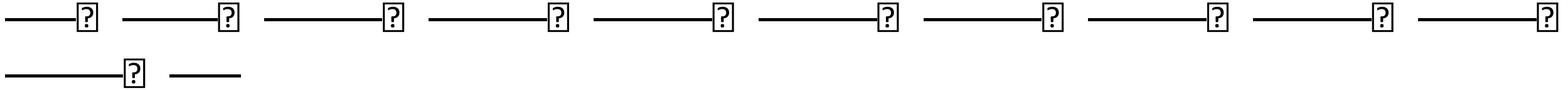
LambdaConf 2024, Estes Park, CO



Background

I write APL code,
primarily a compiler for APL written in APL.
Almost all of it is Loopless,
meaning no syntactic control flow syntax.

It is designed to be:
Data-parallel, GPU-friendly,
Fast,
Maintainable,
Portable.

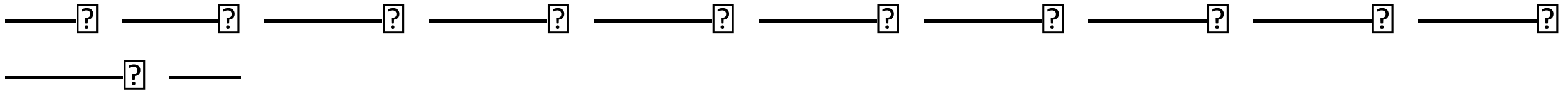


Background

APL is (one of) the best language(s) for this.
Why?

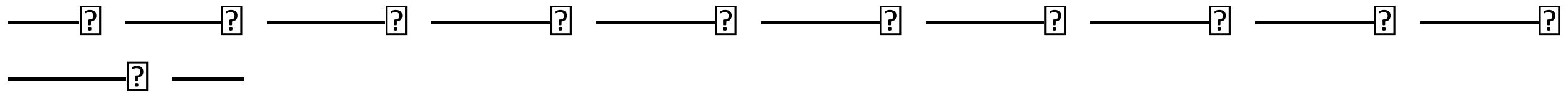
From an HCI/d perspective,
how does APL support
large-scale, data-parallel, loopless software?

What are its unique ergonomic affordances?



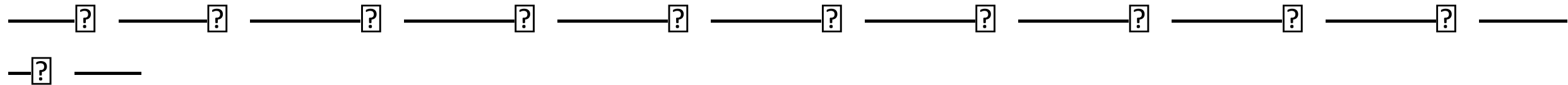
Background

Most people don't "get" APL.
They miss the big picture.



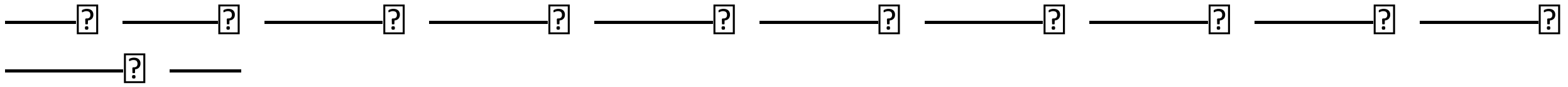
Baseline

This is the part everyone “gets”:



Baseline

	Monadic	Dyadic		Dyadic
+	Conjugate	Plus		$\wedge$ And
-	Negative	Minus		$\vee$ Or
$\times$	Signum	Times		∇ Nand
$\div$	Reciprocal	Divide	∇	Nor
	Magnitude	Residue		$<$ Less than
[	Ceiling	Maximum	$\leq$	Less than or Equal
]	Floor	Minimum		$=$ Equal
*	Exponent	Power		$\geq$ Greater than
$\odot$	Nat Log	Logarithm		$>$ Greater than or Equal
!	Factorial	Binomial		$\neq$ Not Equal



Baseline

$\bar{A}$: Array

Elements: $e_0 e_1 \dots e_{n-1} \in \bar{A}$, $A \mid n \leftrightarrow \not\equiv, A$
 Shape: $d_0 \dots d_{k-1} \in \mathbb{N}$ $\rho A \mid k \leftrightarrow \not\equiv \rho A$
 $d_0 \leftrightarrow \not\equiv A$

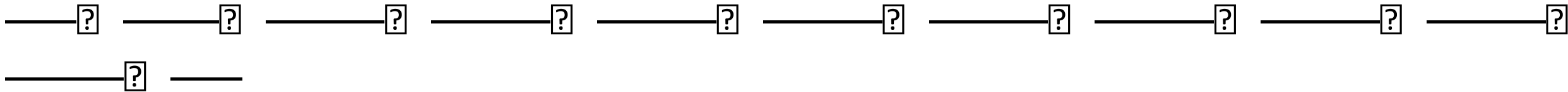
$\equiv Y$ Nesting level of A

$X \equiv Y$ X same as Y

$X \not\equiv Y$ X not same as Y

Scalars $\rightarrow$ Arrays

(make-array (array-shape A)
 (map s-prim (array-elems A)))



Baseline

Dyadic Application

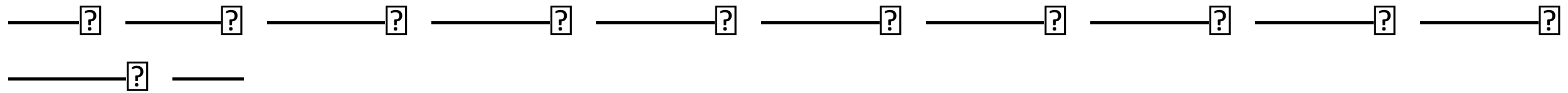
0	1	2	3	4	0	1	2	3	4	0	1	4	9	16		
5	6	7	8	9	0	1	2	3	4	0	6	14	24	36		
10	11	12	13	14	×	0	1	2	3	4	↔	0	11	24	39	56
15	16	17	18	19	0	1	2	3	4	0	16	34	54	76		
20	21	22	23	24	0	1	2	3	4	0	21	44	69	96		



Baseline

Scalar Extension

0	1	2	3	4		0	5	10	15	20
5	6	7	8	9		25	30	35	40	45
10	11	12	13	14	$\times 5 \longleftrightarrow$	50	55	60	65	70
15	16	17	18	19		75	80	85	90	95
20	21	22	23	24		100	105	110	115	120



Baseline

Rank Polymorphic Pointwise Lifting
Scalar Function Primitives



Baseline

Indexing/Assignment

$$A[l_0; \dots; l_{k-1}] \leftarrow X \quad A[l_0; \dots; l_{k-1}] \quad X(f@g)Y$$

$$(f \ A) \leftarrow X \quad l_0 \dots l_{k-1} \sqcap A$$

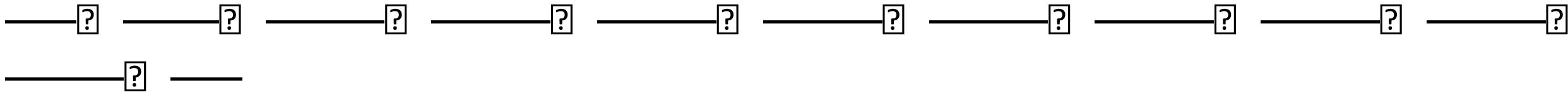
Composition (Points-free/Tacit)

$$X \circ f \circ g \ Y \iff (X \ f \ (g \ Y)) \mid X \ f \sim Y \iff Y \ f \ X \mid X \ f \circ g \ Y \iff f \ (X \ g \ Y)$$

$$A \circ f \ Y \iff (A \ f \ Y) \mid X \ A \sim Y \iff A \mid X \ f \circ g \ Y \iff (g \ X) \ f \ (g \ Y)$$

$$f \circ A \ Y \iff (Y \ f \ A)$$

$$X(f \ g \ h)Y \iff (X \ f \ Y) \ g \ (X \ h \ Y) \mid X \ (f \ g) \ Y \iff f \ (X \ g \ Y)$$



Iteration/Traversal

Pointwise isn't the only pattern...

$\{X\} f''$	Y Each/Map	$f \nparallel$	Y Reduce (First axis)
$\{X\} f[\text{axis}]$	Y Along axis	$f /$	Y Reduce (Last axis)
$X \circ f$	Y Outer product	$X f \nparallel$	Y N-wise reduce (First)
$X f.g$	Y Inner product	$X f /$	Y N-wise reduce (Last)
$\{X\} f \star N$	Y Repeated iteration	$f \searrow$	Y Scan (First axis)
$\{X\} f \star g$	Y "Fixed Point"	$f \backslash$	Y Scan (Last axis)
$\{X\} f \ddot{o} v$	Y Rank		
$\{X\} f \diamond s$	Y Stencil		
$\{X\} f \equiv$	Y Key/Group by		



Manipulation

We need to change the structure of arrays...

X, Y Catenate (Last) $\uparrow Y$ Lift depth $X \uparrow Y$ Take

$\bar{\tau} Y$ Table $\downarrow Y$ Push depth $X \downarrow Y$ Drop

$X \bar{\tau} Y$ Catenate (First)

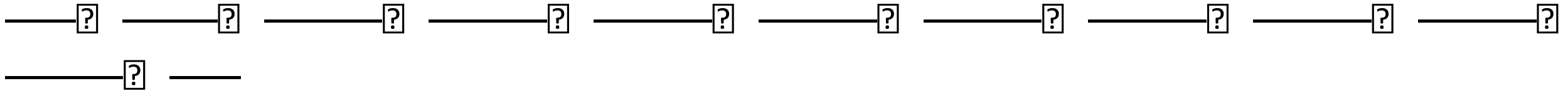
$X \oslash Y$ Transpose

$\oplus Y$ Reverse (Last)

$\ominus Y$ Reverse (First) $\subset Y$ Enclose $X \subset Y$ Enc. Partition

$X \oplus Y$ Rotate (Last) $\subseteq Y$ Nest $X \subseteq Y$ Partition

$X \ominus Y$ Rotate (First) $\in Y$ Flatten



Manipulation

We need to select elements from arrays...

$\supset Y$ First

$X \sim Y$ Without

$X \supset Y$ Pick

$X \cup Y$ Union

X / Y Replicate (Last) $X \cap Y$ Intersection

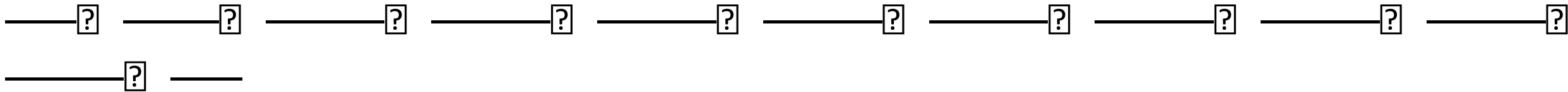
$X \not\sim Y$ Replicate (First) $\neq Y$ Unique Mask

$X \setminus Y$ Expand (Last) $X \in Y$ Membership

$X \not\sim Y$ Expand (First)

$X \vdash Y$ Right

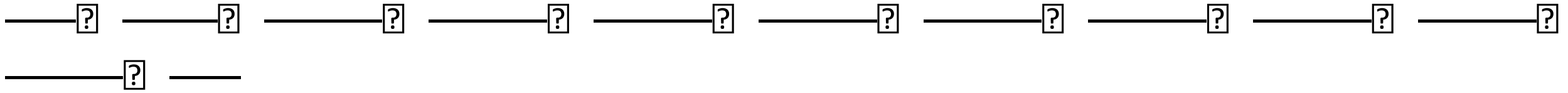
$X \dashv Y$ Left



Theory

Basic CS theory concepts as algorithms (c.f. Conor)...

- ιY Index space of shape Y
- $X \iota Y$ Index of Y in X
- $\underline{\iota} Y$ Indices of non-zeros
- $X \underline{\iota} Y$ Interval in X containing Y
- $\triangleup Y$ Grade up ($V[\triangleup V]$ sorts V)
- ∇Y Grade down
- $? Y$ Roll dice
- $X ? Y$ Deal cards
- $X \in Y$ Find subarrays
- $X \perp Y$ Decode Y as radix X
- $X \top Y$ Encode Y as radix X
- $\boxed{\div} Y$ Matrix Inverse
- $X \boxed{\div} Y$ Matrix Divide



Idioms

That’s the base...where everyone stops.
Solve your problem using only those primitives.

Idioms are the phrases that turn symbols into meaning.

Sub-indices given by X: $\epsilon_{i''X} \leftrightarrow \epsilon_{i''1\ 2\ 3} \leftrightarrow 0\ 0\ 1\ 0\ 1\ 2$

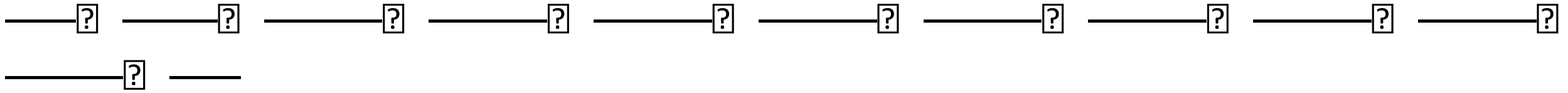
Indices matching predicate: $_B \leftrightarrow _t=F \leftrightarrow _vb>0$

Primes to N: $(2=+\not\div 0=X\circ.\mid X)\not\div X\leftarrow 1+\iota N$

Game of Life: $\supset 1\ \omega V.\wedge 3\ 4=+\not\div,^{-}1\ 0\ 1\circ.\ominus^{-}1\ 0\ 1\circ.\oplus\subset\omega$

Depth to Parent: $p\vdash 2\{p[\omega]\leftarrow\alpha[\alpha_ \omega]\}\not\div\vdash\circ\subset\boxminus d\vdash p\leftarrow\iota\neq d$

RelU 3x3 Convolution: $0[(,[2+\iota 3]\{\omega\}\boxtimes 3\ 3\vdash\omega)+.\times,[\iota 3]\alpha$



Equational Reasoning

Idioms can be expressed with other idioms,
Defined in terms of each other,
Inspire new paths.

They can connect the concept of one primitive to another.



Equational Reasoning

$$x \neq v \leftrightarrow \text{exp} \cdot v$$

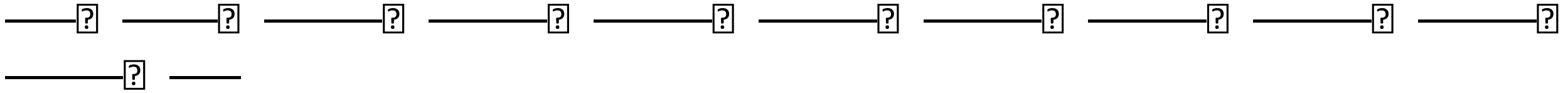
Find j such that

$$(x \neq v)[j] \leftrightarrow v \leftrightarrow (x \neq v)[j+x-1]$$

when $\wedge \neq x > 0$

Exclusive Scan:

$$(+ \neq x) - x$$



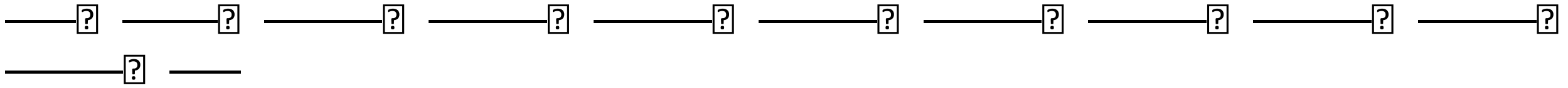
Encoding

It's hard to use idioms if you hide everything behind abstraction.

Thus,

we must learn to encode the domain into arrays.

Maximize the degree to which idioms and primitives have a meaningful interpretation in the encoded domain.



Encoding

Trees

p Parent p[i] is the index into p of the parent of i

t Type t ∈ A F E P

$$\perp (t=E) \wedge t[p]=F$$

“The nodes where the type is an expression and the type of its parent is a function.”

i ∪ p[i] ↔ indices of i matching p[i]

↔ independent tree matching subtree i

APL semantics mean something in the domain of trees now!

No new syntax/abstractions.



Control Flow

Control flow/logic also needs to be encoded.

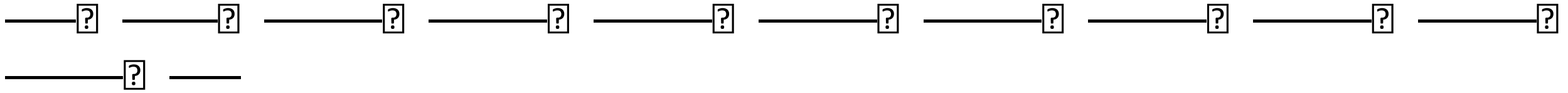
Booleans $\leftrightarrow$ Conditional Behavior/Branching

Indices $\leftrightarrow$ Pointers, Structures, Graphs

Shape $\leftrightarrow$ Partitions, groups

$$\perp(t=E) \wedge t[p]=F$$

Booleans, Iteration, Traversal, Types, Pointers, Relationships, Object IDs



Dependency

Architecture can ruin simplicity.

Simplify architecture by modeling APL data-flow in the large.

Minimize dependencies (edges) in the architecture graph,
aiming for linear > tree > single cycle > [crazy].

Compile: $TK \rightarrow PS \rightarrow TT \rightarrow GC \rightarrow CC \rightarrow LK$

TK: $T_0 \rightarrow T_1 \rightarrow \dots \rightarrow T_n$

PS: $P_0 \rightarrow P_1 \rightarrow \dots \rightarrow P_n$

TT: $C_0 \rightarrow C_1 \rightarrow \dots \rightarrow C_n$



Secret Sauce

Example: Function Specialization

Parsing APL expressions requires type information.
Recursively specialize functions on different types of inputs.

Namespaces:	1	()
Niladic:	1	()
1 st Order (Ambi):	2	(M D)
2 nd Order Monadic:	4	(AM AD FM FD)
2 nd Order Dyadic:	8	(AAM AAD AFM AFD FAM FAD FFM FFD)



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Replication Count

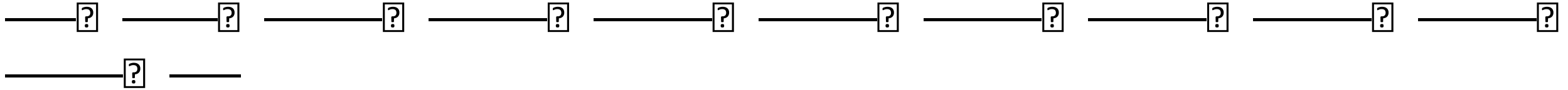
$rc \leftarrow 1 \ 1 \ 2 \ 4 \ 8 [k[i]] @ (i \leftarrow \perp \ t = F) \vdash (\neq p) \rho 1$



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Encoding the recursion

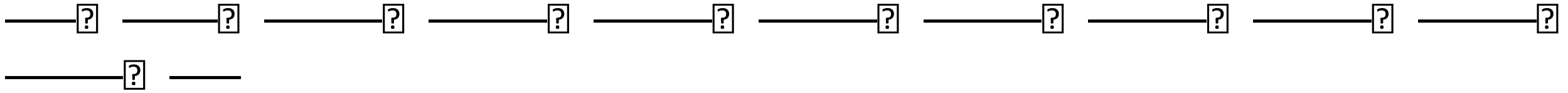
$rc \leftarrow 1 \ 1 \ 2 \ 4 \ 8[k[i]]@(i \leftarrow _t = F) \vdash (\neq p) \rho 1$
 $_ \leftarrow \{r[\omega] \dashv x \times \leftarrow rc[\omega]\} \star \equiv r \dashv x \leftarrow rc$



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Compute group edges and ids (offset)

```
rc←1 1 2 4 8[k[i]]@(i←_t=F)⊢(≠p)ρ1
_←{r[ω]⊢x×←rc[ω]}★≡r⊢x←rc
j←(+↖x)-x ♦ ro←∈l¨x
```



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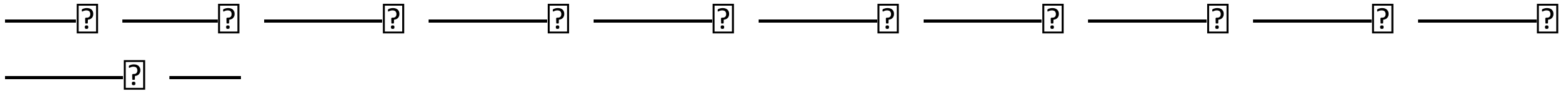
Do the replication

$rc \leftarrow 1 \ 1 \ 2 \ 4 \ 8[k[i]]@(i \leftarrow \perp t=F) \vdash (\neq p)\rho 1$

$_ \leftarrow \{r[\omega] \dashv x \times \leftarrow rc[\omega]\} \star \equiv r \dashv x \leftarrow rc$

$j \leftarrow (+ \setminus x) - x \diamond ro \leftarrow \in \iota \ddot{x}$

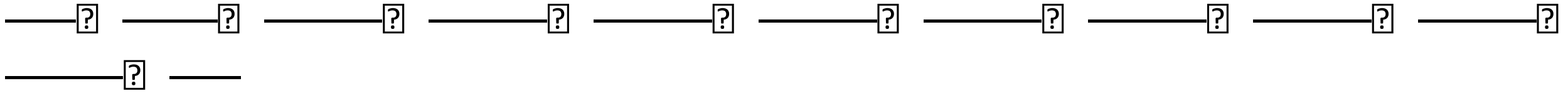
$p \ t \ k \ n \ r \ lx \ vb \ rc \ pos \ end \neq \ddot{\leftarrow} \subset x$



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Update the tree edges

$rc \leftarrow 1 \ 1 \ 2 \ 4 \ 8[k[i]]@(i \leftarrow _t = F) \vdash (\neq p) \rho 1$
 $_ \leftarrow \{r[\omega] \vdash x \times \leftarrow rc[\omega]\} \star \equiv r \vdash x \leftarrow rc$
 $j \leftarrow (+ \setminus x) - x \diamond ro \leftarrow \in \iota \ddot{x}$
 $p \ t \ k \ n \ r \ lx \ vb \ rc \ pos \ end \neq \ddot{\leftarrow} \subset x$
 $p \ r \{j[\alpha] + \omega\} \leftarrow \subset \lfloor ro \div rc$



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Update lexical definition references

$rc \leftarrow 1 \ 1 \ 2 \ 4 \ 8[k[i]]@(i \leftarrow \underline{t}=F) \vdash (\neq p)\rho 1$

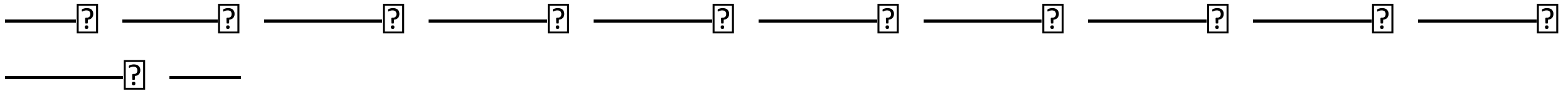
$_ \leftarrow \{r[\omega] \dashv x \times \leftarrow rc[\omega]\} \star \equiv r \dashv x \leftarrow rc$

$j \leftarrow (+ \setminus x) - x \diamond ro \leftarrow \in \iota \ddot{x}$

$p \ t \ k \ n \ r \ lx \ vb \ rc \ pos \ end \not\sim \leftarrow \subset x$

$p \ r \{j[\alpha] + \omega\} \leftarrow \subset \lfloor ro \div rc$

$vb[i] \leftarrow j[vb[i]] + \lfloor ro[i] \div (x \not\sim x)[i] \div x[vb[i \leftarrow \underline{t} vb > 0]]$



Secret Sauce

Tag functions with the appropriate specialization kind

$rc \leftarrow 1 \ 1 \ 2 \ 4 \ 8[k[i]] @ (i \leftarrow \underline{t} = F) \vdash (\neq p) \rho 1$

$_ \leftarrow \{r[\omega] \dashv x \times \leftarrow rc[\omega]\} \star \equiv r \dashv x \leftarrow rc$

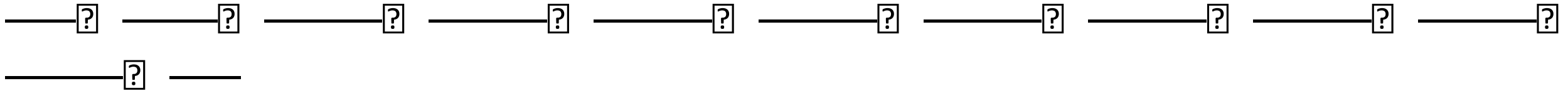
$j \leftarrow (+ \setminus x) - x \diamond ro \leftarrow \in \iota \ddot{x}$

$p \ t \ k \ n \ r \ lx \ vb \ rc \ pos \ end \not\sim \leftarrow \subset x$

$p \ r \{j[\alpha] + \omega\} \leftarrow \subset \lfloor ro \div rc$

$vb[i] \leftarrow j[vb[i]] + \lfloor ro[i] \div (x \not\sim x)[i] \div x[vb[i] \leftarrow \underline{t} vb > 0]]$

$k[i] \leftarrow 0 \ 1 \ 2 \ 4 \ 8[k[i]] (\dashv + \mid) ro[i \leftarrow \underline{t} = F]$



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⊙ Specialize functions to specific formal binding types

$rc \leftarrow 1 \ 1 \ 2 \ 4 \ 8[k[i]] @ (i \leftarrow _t = F) \vdash (\neq p) \rho 1$

$_ \leftarrow \{r[\omega] \vdash x \times \leftarrow rc[\omega]\} \star \equiv r \vdash x \leftarrow rc$

$j \leftarrow (+ \setminus x) - x \diamond ro \leftarrow \in _ x$

$p \ t \ k \ n \ r \ lx \ vb \ rc \ pos \ end \not\sim \leftarrow \subset x$

$p \ r\{j[\alpha] + \omega\} \leftarrow \subset [ro \div rc$

$vb[i] \leftarrow j[vb[i]] + [ro[i] \div (x \not\sim x)[i] \div x[vb[i] \leftarrow _ vb > 0]]$

$k[i] \leftarrow 0 \ 1 \ 2 \ 4 \ 8[k[i]] (\vdash + |) ro[i \leftarrow _ t = F]$

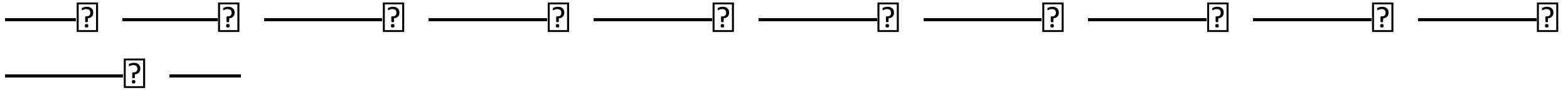


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APL's economy and concision are keys,
they are not incident elements of the value proposition.

This unified economic simplicity and tersity of form
are the first things that people remove from the language
when they try to “improve” the language or borrow from it.

When you make the code small,
many things suddenly get easier.



Secret Sauce

Iverson's Principles of Good Notation

Ease of expressing constructs arising in problems

Suggestivity

Ability to subordinate detail

Economy

Amenability to formal proofs

Thank you. Questions?